

FM 431: Econometrics of Financial Markets

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 İSTANBUL BİLGİ ÜNİVERSİTESİ

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- The slides were produced using \LaTeX and R (the R project; www.R-project.org) on a Linux system.
- Course material is available at www.hs-stat.com/courses/FM431.



Chapter 5:

Models With Trend



5.1 Trends

Series with trends; two examples.

- Key feature of a trend: permanent, non-decaying effect.
- Let's consider two models with trend.
- Each of the two processes results from
 - an assumption about the increment $\Delta y_t = y_t - y_{t-1}$,
 - an assumption about a stochastic perturbation.
- They have a similar structure, but completely different behaviour.



5.1 Trends

Example 1: A model with stationary trend.

- Assumption about increment:

$$\Delta y_t = a_0$$

- The resulting process is perturbed by a stationary component:

$$y_t = y_0 + a_0 t + \alpha(L)\epsilon_t, \quad (\epsilon_t) : \text{white noise}$$

- This is called a trend-stationary model.



5.1 Trends

Example 2: A model with stochastic trend.

- Assumption about increment:

$$\Delta y_t = a_0 + \epsilon_t, \quad (\epsilon_t) : \text{white noise}$$

- The resulting process is:

$$y_t = y_0 + a_0 t + \sum_{i=1}^t \epsilon_i$$

- This is called a model with stochastic trend (or a random walk with drift).



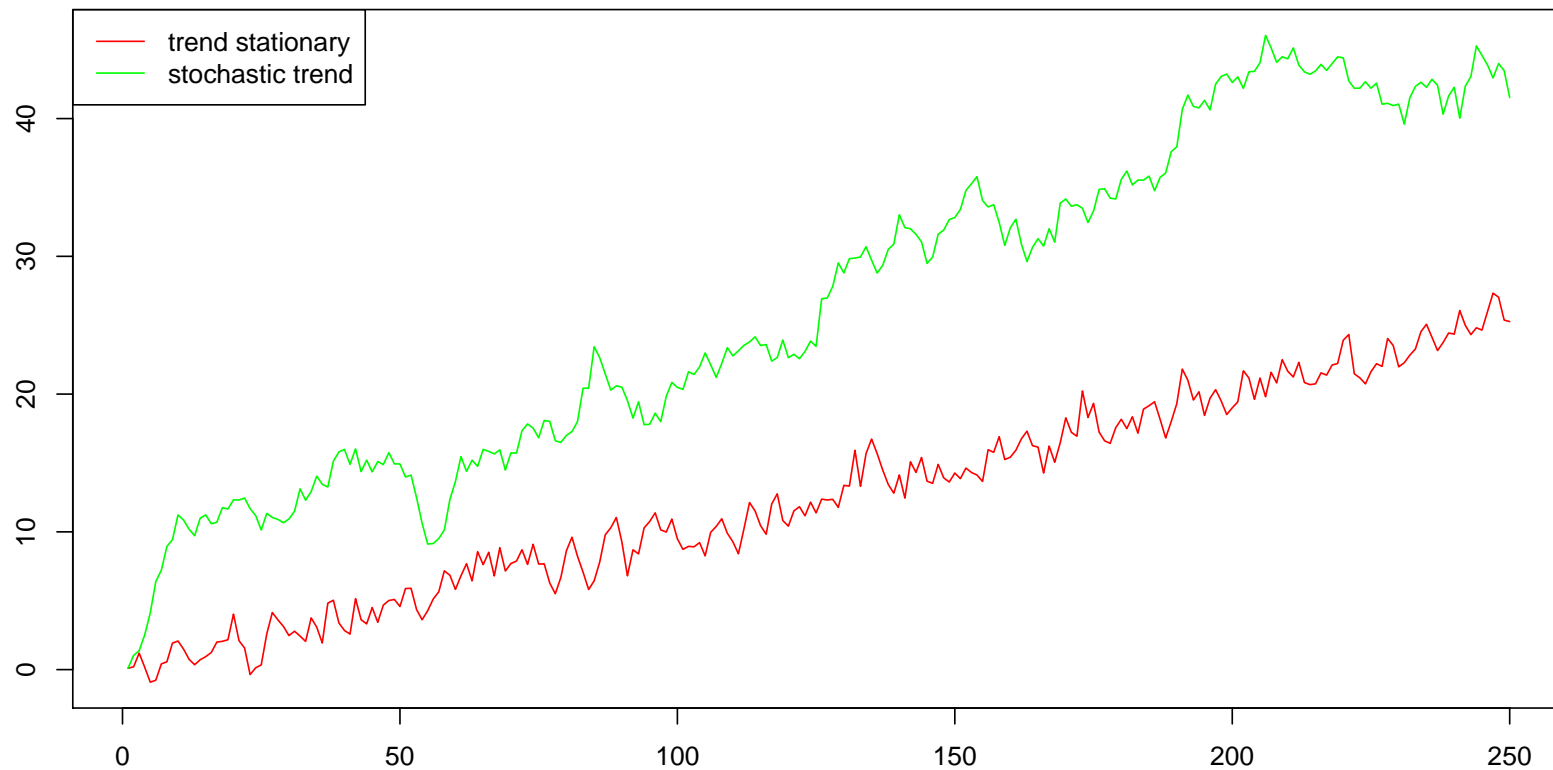
5.1 Trends

- Both models have a term “ a_0t ”.
- Model 2 is perturbed by a random walk.
- We shall now:
 - see simulations of both models,
 - investigate the random walk properties,
 - point out some difficulties with identifying a random walk.



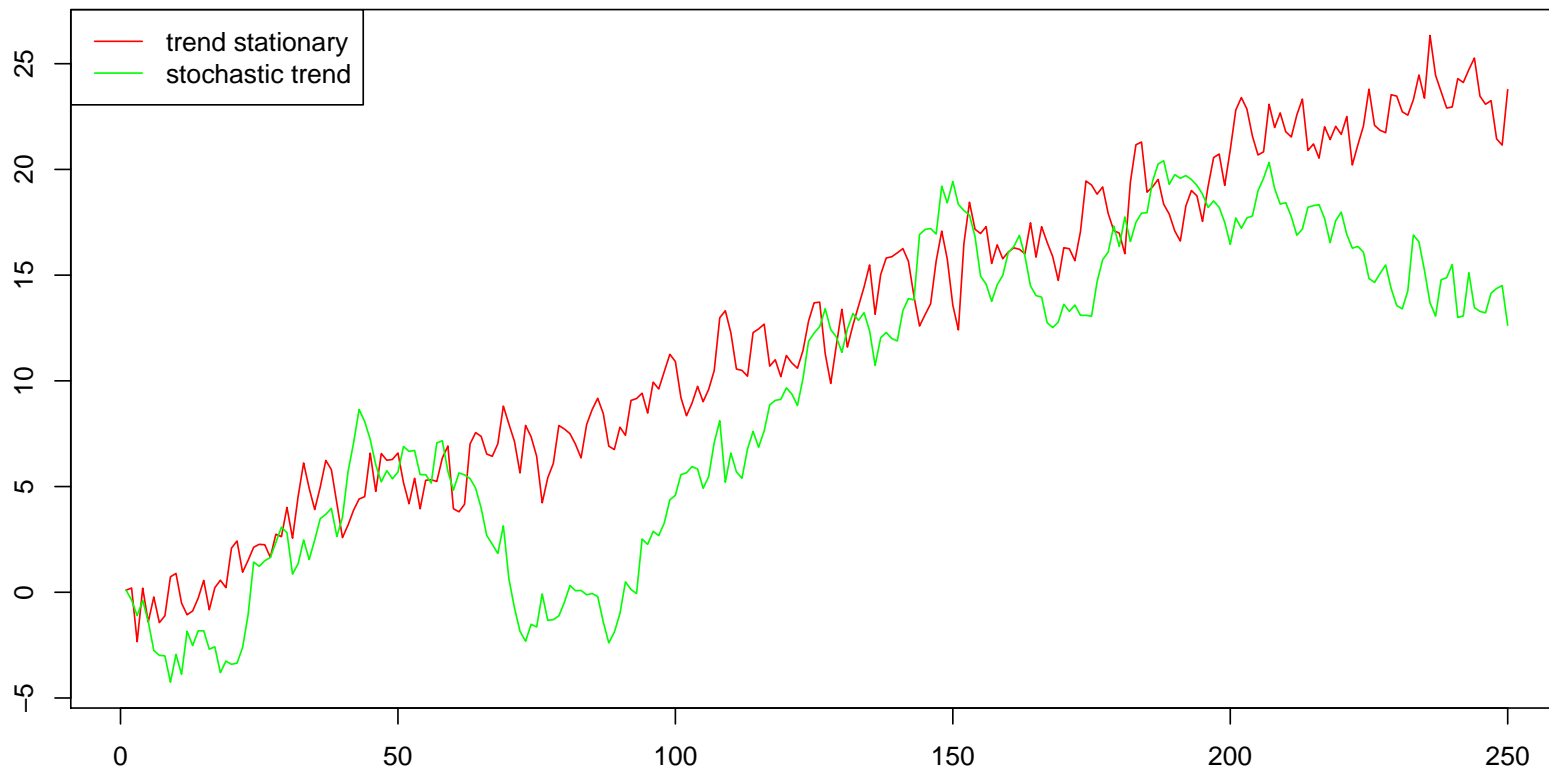
5.1 Trends

A simulation of models 1 and 2.



5.1 Trends

A simulation of models 1 and 2.



5.1 Trends

Properties of a random walk — moments.

- Model:

$$y_t = y_0 + \sum_{i=1}^t \epsilon_i, \quad (\epsilon_t) : \text{white noise with } \text{var}(\epsilon_t) = \sigma_\epsilon$$

- Unconditional moments:

$$E(y_t) = y_0, \quad \text{var}(y_t) = t\sigma_\epsilon^2$$

- Conditional moments:

$$E(y_{t+1}|y_t) = y_t, \quad \text{var}(y_{t+1}|y_t) = \sigma_\epsilon^2$$



5.1 Trends

Properties of a random walk — autocorrelation.

- Covariance:

$$\mathbb{E}[(y_{t+s} - y_0)(y_t - y_0)] = \mathbb{E}\left(\sum_{i=1}^{t+s} \epsilon_i \cdot \sum_{i=1}^t \epsilon_i\right) = t\sigma_\epsilon^2$$

- Correlation:

$$\rho_s = \text{cor}(y_{t+s}, y_t) = \frac{t\sigma_\epsilon^2}{\sqrt{(t+s)\sigma_\epsilon^2} \cdot \sqrt{t\sigma_\epsilon^2}} = \sqrt{\frac{t}{t+s}}$$



5.1 Trends

Autocorrelation of a random walk.

Conclusions.

- $s \mapsto \rho(s)$ is decreasing; similar to the acf of an AR(1) process.
- The speed of decrease will depend on t .
- The acf is not suitable to distinguish a random walk from an AR(1) process.



5.1 Trends

Simulation of a random walk.

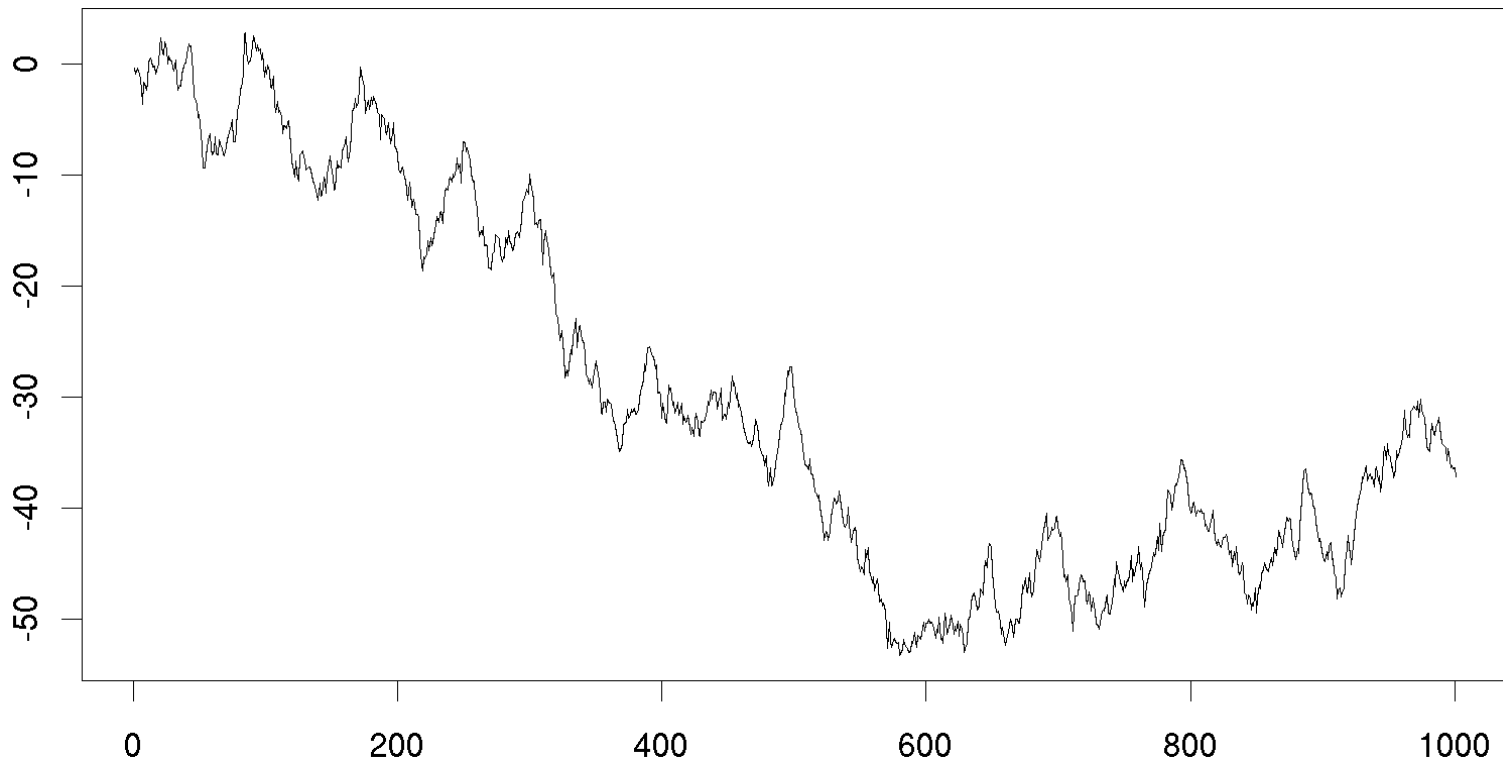
We shall now:

- Simulate a (Gaussian) random walk (y_t) .
- Draw, such that the dependence on t becomes clear:
 - scatterplots of y_t vs. y_{t-1} ,
 - the acf of the simulated series.



5.1 Trends

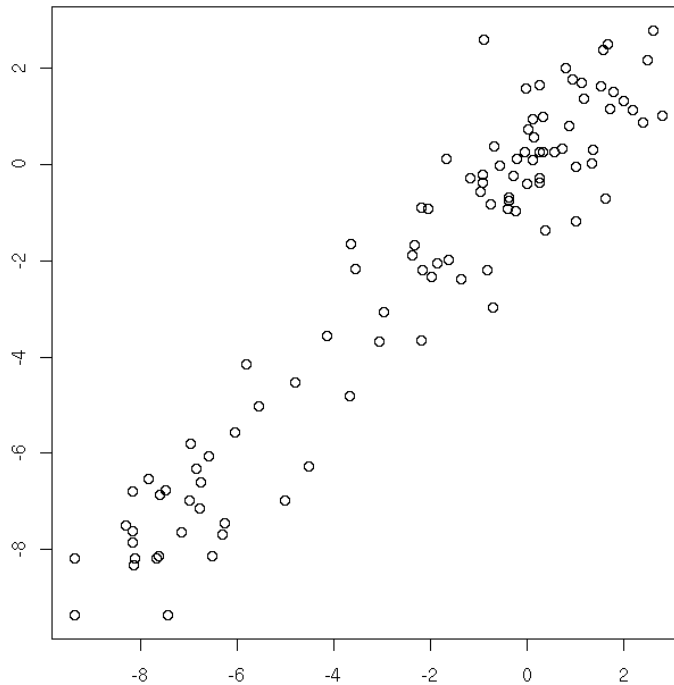
A simulated random walk.



5.1 Trends

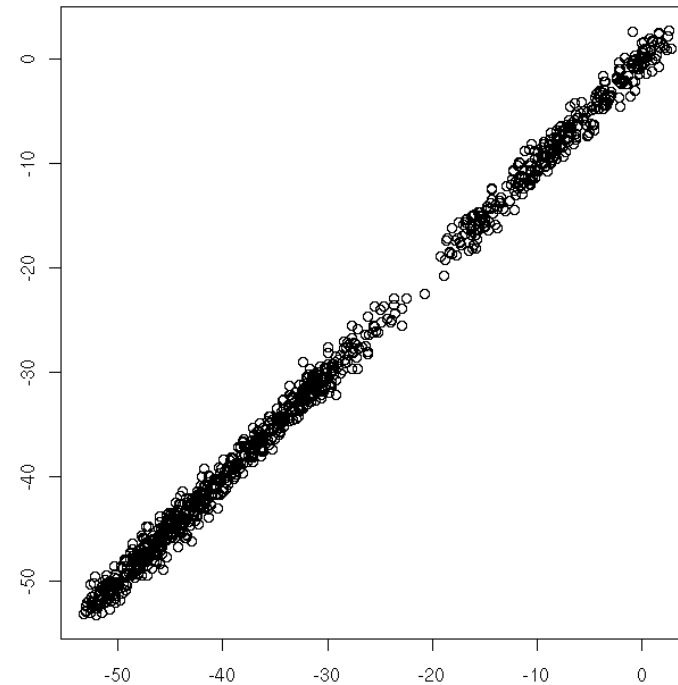
The simulated random walk — scatterplot of y_t vs. y_{t-1} .

First 100 realizations:



correlation: 0.9556

All 1000 realizations:



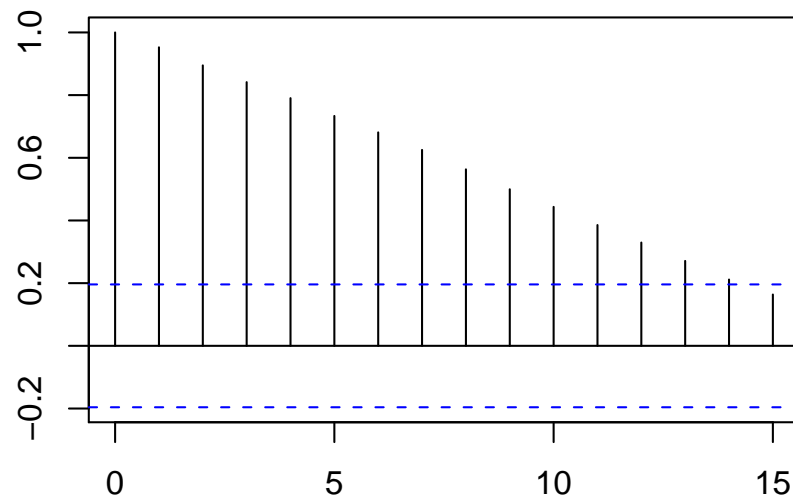
correlation: 0.9982



5.1 Trends

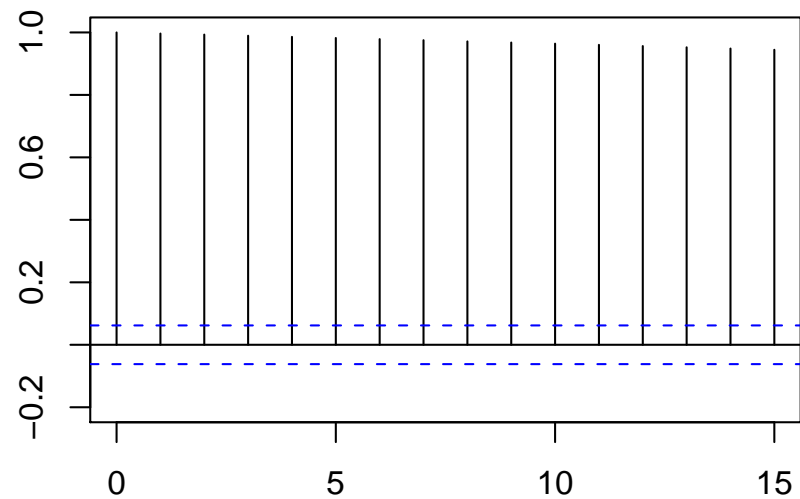
The simulated random walk — autocorrelation function.

First 100 realizations:



autocorrelation (lag 1): 0.9556

All 1000 realizations:



autocorrelation (lag 1): 0.9982



5.1 Trends

Statistical inference.

- Consider the model $y_t = y_0 + ay_{t-1} + \epsilon_t$.
- If $a < 1$, the correlation of y_t and y_{t-1} estimates a .
- If $a = 1$, the correlation of y_t and y_{t-1} underestimates a .
- This is why special tests are needed to test

$$H_0 : a = 1 \quad \text{against} \quad H_1 : a < 1.$$



5.1 Trends

News impact.

- One reason why it is important to distinguish between random walk and AR(1): News impact is different.
- AR(1): $y_t = a_0 + a_1 y_{t-1} + \epsilon_t$. Then:

$$y_t = \frac{a_0}{1 - a_1} + \sum_{i=0}^{\infty} a_1^i \epsilon_{t-i}, \quad \text{so: } \frac{\partial y_{t+s}}{\partial \epsilon_t} = a_1^s.$$

- Random walk: $y_t = y_{t-1} + \epsilon_t$. Then:

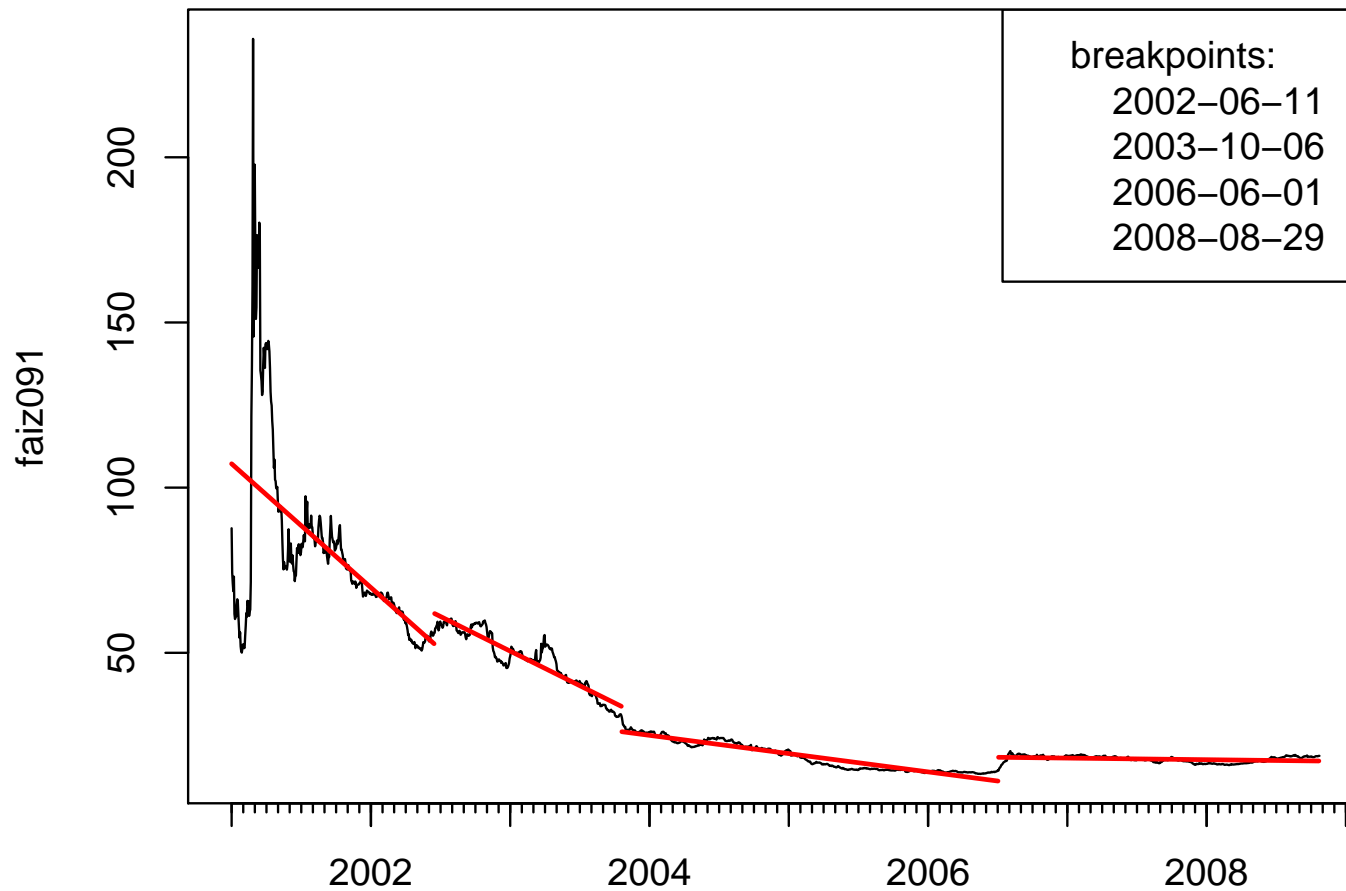
$$y_t = y_0 + \sum_{i=1}^t \epsilon_i, \quad \text{so: } \frac{\partial y_{t+s}}{\partial \epsilon_t} = 1.$$

Permanent, but random, change in mean, justifies the term “stochastic trend”.



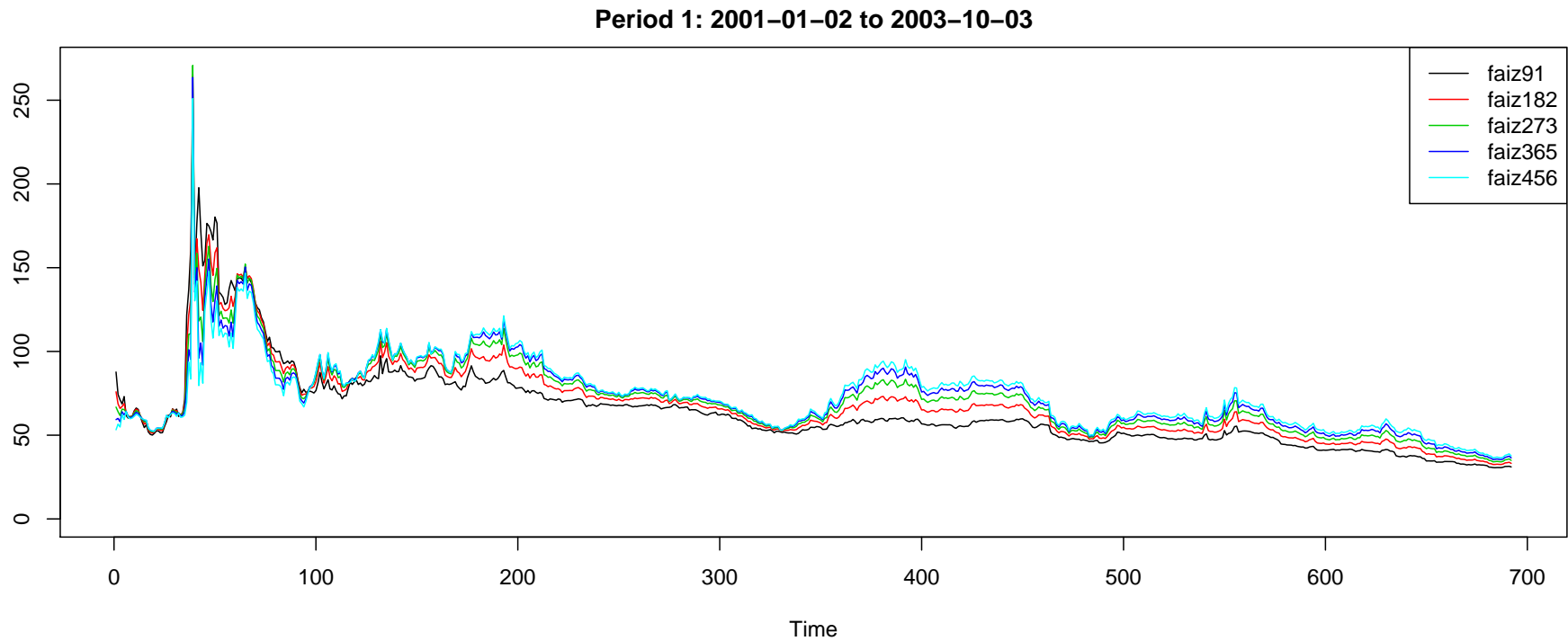
Some Figures

Interest Rate in Turkey.



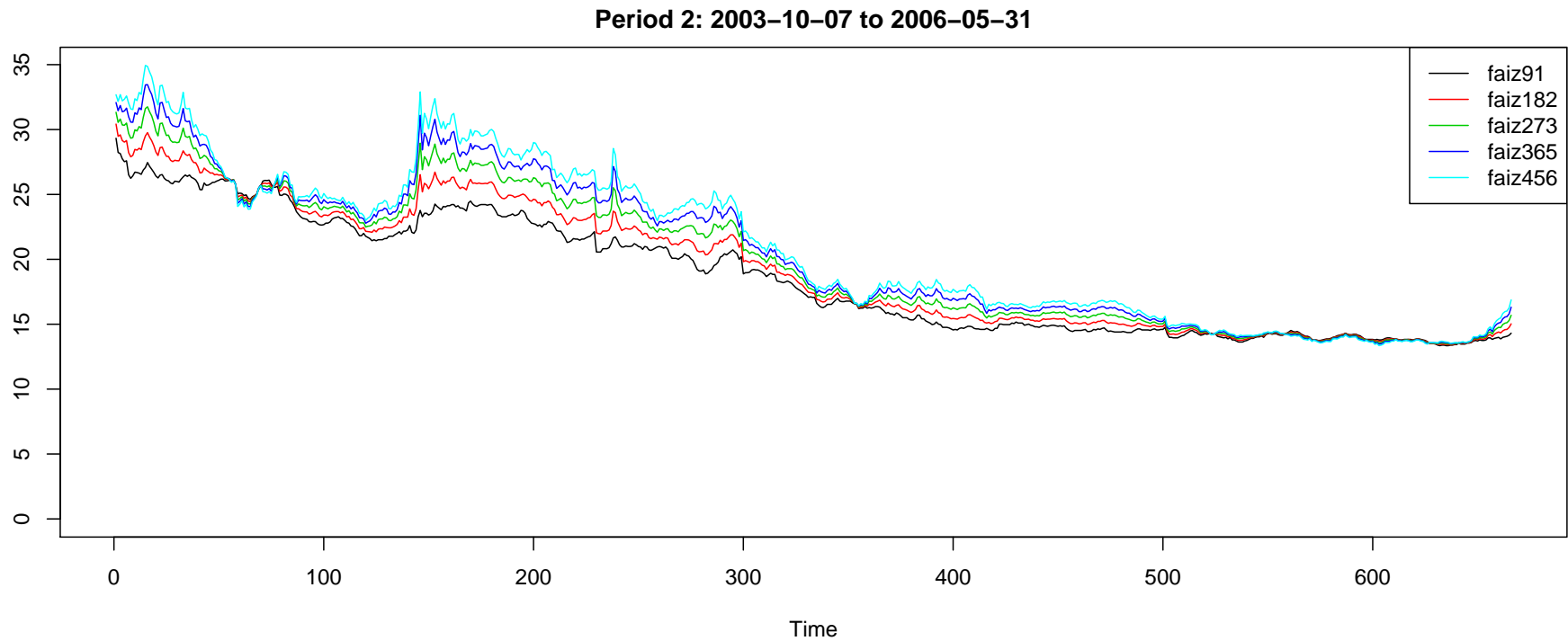
Some Figures

Interest Rate in Turkey.



Some Figures

Interest Rate in Turkey.



Some Figures

Interest Rate in Turkey.

